

this problem. However, the large write head gaps that are needed for good overwrite of high coercivity media lead to excessive fringing, negatively affecting the data written on adjacent tracks.

Perpendicular (vertical) magnetic recording media have been proposed as a way
5 to increase areal densities beyond 100 Gb/in². Perpendicular magnetic recording media include a magnetic recording layer having an easy magnetization axis that is substantially perpendicular to the magnetic layer. A perpendicular write head, such as a monopole write head or a shielded pole write head, is utilized to magnetize the grains in the perpendicular recording layer. Examples of perpendicular recording media and
10 perpendicular write heads are disclosed in U.S. Patent No. 4,656,546 by Mallary and U.S. Patent No. 4,748,525 by Perlov, which are incorporated herein by reference in their entirety.

The write head for perpendicular recording includes a write pole and a return pole that is coupled to the write pole. An electrically conductive magnetizing coil
15 surrounds the yoke of the write pole to switch the polarity of the magnetic field applied to the write pole. During operation, the recording head flies above the magnetic recording medium by a distance referred to as the fly height. An electrical current is passed through the coil to create a magnetic flux within the write pole. The magnetic flux passes from the write pole tip through the magnetic recording layer and into a
20 magnetically soft underlayer disposed beneath the magnetic recording layer. The soft magnetic underlayer causes the magnetic flux to pass across to the return pole. In addition, the soft underlayer produces magnetic charge images of the magnetic recording layer during read operations, increasing the magnetic flux and increasing the playback signal.

25 Perpendicular recording media can support higher areal densities than conventional longitudinal media, in part due to reduced demagnetizing fields in the recording transitions. While substantial advances have been made, further improvements in the magnetic recording media are necessary for the practical implementation of perpendicular magnetic recording devices. For example, the soft
30 underlayer domains contribute to noise and lead to a lower signal-to-noise ratio (SNR).

The magnetic domains in the soft underlayer also increase spike noises. Further, the remnant magnetization from the soft underlayer can lead to distortions in the giant magnetoresistive (GMR) read sensitivity. Therefore, the soft underlayer should have high magnetization and permeability from the writing point of view and almost zero remnant magnetization from the reading point of view.

U.S. Patent Application Publication No. U.S. 2002/0028357 by Shukh et al. discloses a perpendicular magnetic recording medium with anti-ferro magnetic coupling in a soft magnetic underlayer. The soft magnetic underlayer includes a first magnetic soft layer, a first interface layer on the first magnetic soft layer, a second magnetic soft layer, a second interface layer on a second magnetic soft layer and a non-magnetic coupling layer between the first interface layer and the second interface layer.

U.S. Patent Application Publication No. US 2003/0022023 by Carey et al. discloses a dual-layered type perpendicular magnetic recording disk for use in a perpendicular magnetic recording system. The magnetic recording disk includes a laminated underlayer that has at least two ferromagnetic films exchange-coupled across an anti-ferromagnetic coupling layer. The magnetic moments of the ferromagnetic layers in the laminated underlayer are oriented anti-parallel.

During the repeated application of magnetic fields from the head to write information on any particular track on the recording media, the leakage fields from the head can erase the information written on the adjacent tracks. This adjacent track erasure is considered to be a major hurdle to the implementation of perpendicular recording, particularly due to the magnification of head leakage fields by the magnetically soft underlayer that is necessary for perpendicular recording media.

There remains a need for an improved perpendicular recording medium having improved signal-to-noise ratio (SNR), a decreased pulse width (PW₅₀) and reduced adjacent track erasure.

Brief Summary of the Invention

The present invention provides an improved perpendicular recording medium. The recording medium consists of at least a pair of soft magnetic layers, which are anti-parallel coupled through a non-magnetic coupling layer, such as a ruthenium (Ru) layer.

5 The remnant magnetization of the soft underlayer structure is substantially reduced compared to conventional soft underlayer structures, leading to a reduction of domain noise. The magnetic anisotropy of the soft underlayer is controlled by adjusting the thickness of the magnetically soft underlayers, which results in different magnitudes of anti-parallel exchange field. The structure according to the present invention can

10 advantageously decrease the pulse width (PW₅₀), improve the signal-to-noise ratio (SNR) and reduce adjacent track erasure.

According to one embodiment of the present invention, a magnetic recording medium for perpendicular recording is provided. The magnetic recording medium includes a substrate, an underlayer structure disposed over the substrate, an intermediate layer disposed over the underlayer structure and a perpendicular magnetic recording layer disposed over the intermediate layer. The underlayer structure includes a first soft magnetic underlayer having a first thickness, a second soft magnetic underlayer disposed over the first soft underlayer and having a second thickness, wherein the first thickness is greater than the second thickness. A non-magnetic spacer layer is disposed between the first and second soft magnetic underlayers and the first and second soft magnetic underlayers are anti-parallel coupled through the non-magnetic spacer layer.

According to another embodiment of the present invention, a magnetic recording medium for perpendicular recording is provided. The magnetic recording medium includes a substrate, an underlayer structure disposed over the substrate, an intermediate layer disposed over the underlayer structure and a perpendicular magnetic recording layer disposed over the intermediate layer. The underlayer structure includes a first soft magnetic underlayer having a first thickness, a second soft magnetic underlayer and a third soft magnetic underlayer disposed over the first soft underlayer.

30 A first non-magnetic spacer layer is disposed between the first and second soft

magnetic underlayers and a second non-magnetic spacer layer is disposed between the second and third soft magnetic underlayers. The second and third soft magnetic underlayers are anti-parallel coupled through the second non-magnetic spacer layer.

According to another embodiment of the present invention, a magnetic recording medium for perpendicular recording is provided. The magnetic recording medium includes a substrate, an underlayer structure, an intermediate layer disposed over the underlayer structure and a perpendicular magnetic recording layer disposed over the intermediate layer. The underlayer structure includes a first soft magnetic underlayer having a first saturation magnetization (M_s) and a second soft magnetic underlayer having a second saturation magnetization, where the second saturation magnetization is greater than the first saturation magnetization. A spacer layer is disposed between the first and second soft magnetic underlayers.

Brief Description of the Drawings

Fig. 1 illustrates a top plan view of a disk drive device.

Fig. 2 illustrates a cross-sectional view of a perpendicular recording medium according to an embodiment of the present invention.

Fig. 3 illustrates a schematic view of a perpendicular write head and a perpendicular recording medium according to an embodiment of the present invention.

Fig. 4 illustrates M-H loops along radial and circumferential directions for a conventional soft underlayer and a soft underlayer according to an embodiment of the present invention.

Fig. 5 illustrates the exchange field and anisotropy field as a function of the second underlayer thickness for a soft underlayer structure according to an embodiment of the present invention.

Fig. 6 illustrates a cross-sectional view of a perpendicular recording medium according to the present invention.

Fig. 7 illustrates the adjacent track erasure for a magnetic recording medium utilizing a conventional soft underlayer and a magnetic recording medium utilizing a soft underlayer structure according to an embodiment of the present invention.

Fig. 8 illustrates the signal to noise ratio (SNR) for a recording media fabricated using a conventional soft underlayer and a soft underlayer according to an embodiment of the present invention.

Fig. 9 illustrates a cross-sectional view of a perpendicular recording medium 5 according to an embodiment of the present invention.

Detailed Description of the Invention

The present invention is directed to a magnetic recording medium including a perpendicular magnetic recording layer. As used herein, a perpendicular magnetic recording layer is a magnetic recording layer where the magnetic grains have an easy magnetization axis that is oriented substantially perpendicular to the plane of the layer (i.e., the radial axis). The magnetic recording medium can be, for example, a magnetic tape or a magnetic hard disk, and in a preferred embodiment is a magnetic hard disk, such as for use in a disk drive.

Fig. 1 illustrates one embodiment of a disk drive 110. The disk drive 110 generally includes a base plate 112 and a cover (not shown) that may be disposed on the base plate 112 to define an enclosed housing or space for the various disk drive components. The disk drive 110 includes one or more data storage disks 114 of any appropriate computer-readable data storage media. Typically, both of the major 10 surfaces of each data storage disk 114 include a plurality of concentrically disposed tracks for data storage purposes. Each disk 114 is mounted on a hub or spindle 116, which in turn is rotatably interconnected with the disk drive base plate 112 and/or cover. Multiple data storage disks 114 are typically mounted in vertically spaced and parallel 20 relation on the spindle 116. Rotation of the disk(s) 114 is provided by a spindle motor 118 that is coupled to the spindle 116 to simultaneously spin the data storage disk(s) 25 114 at an appropriate rate.

The disk drive 110 also includes an actuator arm assembly 120 that pivots about a pivot bearing 122, which in turn is rotatably supported by the base plate 112 and/or cover. The actuator arm assembly 120 includes one or more individual rigid actuator

arms **124** that extend out from near the pivot bearing **122**. Multiple actuator arms **124** are typically disposed in vertically spaced relation, with one actuator arm **124** being provided for each major data storage surface of each data storage disk **114** of the disk drive **110**. Other types of actuator arm assembly configurations could be utilized as well, such as an "E" block having one or more rigid actuator arm tips or the like that cantilever from a common structure. In any case, movement of the actuator arm assembly **120** is provided by an actuator arm drive assembly, such as a voice coil motor **126** or the like. The voice coil motor **126** is a magnetic assembly that controls the operation of the actuator arm assembly **120** under the direction of control electronics **128**. Any appropriate actuator arm assembly drive type may be utilized by the disk drive **110**, including a linear drive (for the case where the actuator arm assembly **120** is interconnected with the base plate **112** and/or cover for linear movement versus the illustrated pivoting movement about the pivot bearing **122**) and other types of rotational drives.

15 A load beam or suspension **130** is attached to the free end of each actuator arm **124** and cantilevers therefrom. Typically, the suspension **130** is biased generally toward its corresponding disk **114** by a spring-like force. A slider **132** is disposed at or near the free end of each suspension **130**. What is commonly referred to as the read/write head (e.g., transducer) is appropriately mounted on the slider **132** and is used in disk drive read/write operations.

20 The head on the slider **132** may utilize various types of read sensor technologies such as anisotropic magnetoresistive (AMR), giant magnetoresistive (GMR), tunneling magnetoresistive (TuMR), other magnetoresistive technologies, or other suitable technologies. AMR is due to the anisotropic magnetoresistive effect with a normalized change in resistance ($\Delta R/R$) of 2 – 4%. GMR results from spin-dependent scattering mechanisms between two (or more) magnetic layers. The typical use in recording heads is the spin valve device that uses a pinned magnetic layer and a free layer to detect external fields. The normalized change in on-wafer resistance is typically 8 – 12%, but can be as large as 15 – 20% when used with specular capping layers and spin-filter layers. TuMR is similar to GMR, but is due to spin dependent tunneling

currents across an isolation layer. The typical embodiment includes a free layer and a pinned layer separated by an insulating layer of Al_2O_3 with the current flowing perpendicular to the film plane, producing normalized change in resistance of 12 – 25%. The term magnetoresistive is used in this application to refer to all these types of 5 magnetoresistive sensors and any others in which a variation in resistance of the sensor due to the application of an external magnetic field is detected. The read/write head of the present invention is discussed in further detail below.

The biasing forces exerted by the suspension **130** on its corresponding slider **132** moves the slider **132** in the direction of its corresponding disk **114**. Typically, this 10 biasing force is such that if the slider **132** were positioned over its corresponding disk **114**, without the disk **114** being rotated at a sufficient velocity, the slider **132** would be in contact with the disk **114**.

The head on the slider **132** is connected to a preamplifier **133**, which is interconnected with the control electronics **128** of the disk drive **110** by a flex cable **134** 15 that is typically mounted on the actuator arm assembly **120**. Signals are exchanged between the head and its corresponding data storage disk **114** for disk drive read/write operations. In this regard, the voice coil motor **126** is utilized to pivot the actuator arm assembly **120** to simultaneously move the slider **132** along a path **136** and “across” the corresponding data storage disk **114** to position the head at the desired/required radial 20 position on the disk **114** (i.e., at the approximate location of the correct track on the data storage disk **114**) for disk drive read/write operations.

When the disk drive **110** is not in operation, the actuator arm assembly **120** is pivoted to a “parked position” to dispose each slider **132** generally at or beyond a perimeter of its corresponding data storage disk **114**, but in any case in vertically 25 spaced relation to its corresponding disk **114**. This is commonly referred to in the art as being a dynamic load/unload disk drive configuration. In this regard, the disk drive **110** includes a ramp assembly **138** that is disposed beyond a perimeter of the data storage disk **114** to typically both move the corresponding slider **132** vertically away from its corresponding data storage disk **114** and to also exert somewhat of a retaining force on 30 the actuator arm assembly **120**. Any configuration for the ramp assembly **138** that

provides the desired "parking" function may be utilized. The disk drive 110 could also be configured to be of the contact start/stop type, where the actuator arm assembly 120 would pivot in a direction to dispose the slider(s) 132 typically toward an inner, non-data storage region of the corresponding data storage disk 114. Terminating the rotation of

5 the data storage disk(s) 114 in this type of disk drive configuration would then result in the slider(s) 132 actually establishing contact with or "landing" on its corresponding data storage disk 114, and the slider 132 would remain on the disk 114 until disk drive operations are re-initiated.

The slider 132 of the disk drive 110 may be configured to "fly" on an air bearing 10 during rotation of its corresponding data storage disk(s) 114 at a sufficient velocity. The slider 132 may be disposed at a pitch angle such that its leading edge is disposed further from its corresponding data storage disk 114 than its trailing edge. The read/write head would typically be incorporated on the slider 132 generally toward its trailing edge since this is positioned closest to its corresponding disk 114. Other pitch 15 angles/orientations could also be utilized for flying the slider 132.

The present invention is directed to perpendicular recording media, such as one that is useful in a disk drive device as illustrated in Figure 1. The perpendicular recording media includes a perpendicular magnetic recording layer and a multi-layer soft underlayer structure disposed beneath the magnetic recording layer.

20 Fig. 2 illustrates a cross-sectional view of a perpendicular magnetic recording medium according to an embodiment of the present invention that is useful in a disk drive device. The magnetic recording medium 200 includes multiple layers that are deposited upon a rigid substrate 202. Among the layers disposed on the rigid substrate 202 is a perpendicular magnetic recording layer 214. Disposed between the substrate 25 202 and the perpendicular magnetic recording layer 214 is a soft underlayer structure 216 in accordance with an embodiment of the present invention. Disposed between the soft underlayer structure 216 and the magnetic recording layer 214 is an intermediate layer 212. Through the use of this multi-layer soft underlayer structure, the perpendicular magnetic recording layer 214 can have significantly improved magnetic

properties, enabling an increase in the areal density of the perpendicular magnetic recording medium.

The rigid substrate **202** can be fabricated from a number of materials known to those skilled in the art to be useful for magnetic recording media such as hard disks. A 5 particularly preferred material for the rigid substrate **202** according to the present invention is aluminum (Al) coated with a layer of nickel phosphorous (NiP). However, it will be appreciated that the rigid substrate can also be fabricated from other materials, such as glass and glass-containing materials, including glass-ceramics. The rigid substrate **202** typically has an average thickness in the range of from about 10 mils to 10 about 75 mils (about 0.254 millimeter to 1.9 millimeter) and has a smooth surface upon which the remaining layers can be deposited.

The soft underlayer structure **216** comprises a first soft magnetic underlayer **206** deposited over the substrate and a non-magnetic spacer **208** deposited over the first soft magnetic layer **206**, and a second soft magnetic layer **210** deposited over the 15 spacer **208**. The soft magnetic layers **206** and **210** have a high permeability and a low coercivity. Preferably, the soft magnetic layers have a coercivity of not greater than about 10 oersteds (Oe) and a magnetic permeability of at least about 50. For example, the soft magnetic underlayers can be fabricated from soft magnetic materials such as CoZrNb, CoZrTa, FeCoB and FeTaC. It will be appreciated that the soft underlayers 20 and **206** and **210** can be fabricated from the same soft magnetic material, or from different soft magnetic materials.

The spacer layer **208** (or coupling layer) is fabricated from a non-magnetic material. Examples of non-magnetic materials include ruthenium (Ru), rhenium (Re), rhodium (Rh), chromium (Cr) and copper (Cu). Preferably, the spacer layer **208** is 25 fabricated from Ru. The thickness of the non-magnetic spacer layer is selected to provide antiferromagnetic coupling between the two soft underlayers. The thickness of the spacer layer **208** causes the magnetization in the soft magnetic underlayers to be coupled in opposite directions (anti-parallel). According to one embodiment, the thickness of the spacer layer can be from about 0.5 nanometers to about 2 nanometers.

According to the present invention, the first soft underlayer **206** (disposed closest to the substrate) has an average thickness that is greater than the average thickness of the second soft underlayer **210**. In one embodiment, the thickness of the second soft underlayer **210** is from about 10 percent to about 40 percent of the total thickness of the 5 soft underlayer structure **216**, which preferably has a total thickness of from about 50 nanometers to about 300 nanometers. In one embodiment, the thickness of the first soft underlayer can be from about 50 to 150 nanometers and the thickness of the second soft underlayer can be from about 10 nanometers to about 40 nanometers.

Disposed over the soft underlayer structure **216** is an intermediate layer **212**. 10 The thickness of the intermediate layer can preferably be from about 2 to about 50 nanometers. The intermediate layer **212** can be fabricated from materials such as, for example, Ru, Cr, Ta, Ni, Al or other alloys that result in good growth properties of the perpendicular magnetic layer **214**. According to a preferred embodiment, the intermediate layer comprises two distinct sub-layers, such as a seedlayer of Ta, Ti or 15 their alloys and having a thickness of from about 1 to 3 nanometers and an adjacent Ru or Ru alloy (e.g., RuCr) sub-layer having a thickness of from about 5 to about 40 nanometers, with the Ru or Ru alloy sub-layer being disposed adjacent to the magnetic recording layer.

The perpendicular magnetic recording layer **214** is deposited over the 20 intermediate layer **212**. The magnetic recording layer **214** has an easy magnetization axis (e.g., the C-axis) that is oriented perpendicular to the surface of the magnetic recording layer **214**. Useful materials for the magnetic recording layer **214** include cobalt-based alloys having a hexagonal close packed (hcp) structure. Cobalt can be alloyed with elements such as chromium (Cr), platinum (Pt), boron (B), niobium (Nb), 25 tungsten (W) and tantalum (Ta). In one preferred embodiment, the magnetic recording layer **214** includes cobalt alloyed with chromium (CoCr). As used herein, the term CoCr alloys can include alloys having other components in addition to Co and Cr. For example, a CoCr alloy can also include platinum (CoCrPt) and the CoCrPt alloy can include other elements such as boron (CoCrPtB). In addition, the magnetic recording 30 layer can comprise an oxide, such as a CoCrPt-oxide or a CoCrPtB-oxide. Such oxides can further include silicon (Si), such as a CoCrPtSi-oxide or a CoCrPtBSi-oxide. The

magnetic recording layer 214 preferably has an average thickness of at least about 1 nanometer, such as from about 15 nanometers to about 30 nanometers.

The perpendicular magnetic recording medium 200 can also include a protective layer (not illustrated) such as a protective carbon layer and a lubricant layer disposed 5 over the protective layer. These layers are adapted to reduce damage from the read/write head interactions with the recording medium during start/stop operations.

The first and second soft underlayers are anti-parallel coupled through the non-magnetic spacer layer. As is illustrated in Fig. 3, during the writing process (Fig. 3a), a perpendicular write head 302a floats above the perpendicular recording medium 304a. 10 The perpendicular write head 302a includes a write pole 306a coupled to a read pole 308a, with an electromagnetic coil 310a wrapped around the write head. The perpendicular recording medium 304a includes a soft underlayer structure 312a having a first soft underlayer 314a that is thicker than the second soft underlayer 316a and is separated therefrom by a non-magnetic spacer layer 318a. An intermediate layer 320a 15 separates the soft underlayer structure 312a from the perpendicular magnetic recording layer 322a. As is illustrated in Fig. 3(a), both of the soft underlayers are magnetized in a parallel configuration during the write operation.

During the read-back process, as illustrated in Fig. 3b, the two soft underlayers 314b and 316b are anti-parallel coupled, resulting in nearly zero net remanence 20 magnetization. The readback process includes the use of a GMR (giant magnetoresistive) sensor 324b.

The layers of the magnetic recording media according to the present invention can be deposited on the substrate using known deposition techniques. For example, the deposition of the layers under the substrate can be accomplished by physical vapor 25 deposition, e.g., sputtering. Sputtering can be accomplished using gases such as Ar, Kr or Xe. Oxygen can be included in the sputtering gas (reactive sputtering) to form an oxide phase for the magnetic layer. For the underlayer and the magnetic recording layer, it is preferred to sputter at a pressure of from about 2 mTorr to about 150 mTorr. The substrate can be heated prior to sputtering and can be annealed after one or more 30 of the layers has been deposited to relieve residual stresses.

The advantage of the foregoing embodiment with respect to soft underlayer (SUL) noise reduction can be explained as follows. The soft underlayer increases writability of the perpendicular media by increasing the write field magnitude and write field gradient. However, the domains in the soft underlayer contribute to the noise.

5 Also, stray fields in a disk drive can be magnified by the soft underlayer, causing the erasure of written bits. A higher magnetic anisotropy in the soft under layer is essential to reduce these problems, as described by Y. Nakatani, N. Hayashi, Y. Uesaka, and H. Fukushima in "Effect of anisotropy field in soft magnetic underlayer on read/write properties in perpendicular recording media", Journal of Applied Physics, Vol. 93, May
10 2003. An ideal soft underlayer should have a high magnetic anisotropy field (H_k) with an easy magnetization axis along the radial direction. The magnetic anisotropy field is a material property and increasing the anisotropy field leads to higher coercivity, whereas the coercivity of soft underlayer should be low, such as not greater than about 20 Oe. Therefore, for a conventional soft underlayer, the magnetic anisotropy field can not be
15 increased without adversely effecting the coercivity and remnant magnetization.

For the exchange coupled soft underlayer, the anisotropy field is defined as:

$$H_k = (H_k)_{\text{material}} + H_{\text{ex}}$$

where $(H_k)_{\text{material}}$ is the material property and H_{ex} is the exchange field between the first soft underlayer and the second soft underlayer.

20 Fig. 4 illustrates the M-H loops for a conventional soft underlayer (Fig. 4a) and a soft underlayer according to the present invention (Fig. 4b). Each example demonstrates magnetic anisotropy, with the radial axis being the easy magnetization axis and the circumferential direction being the hard magnetization axis. For a conventional soft underlayer, the conferential M-H curve saturates at about 30 Oe, 25 which corresponds to the anisotropy field. On the other hand, the anisotropy field for a soft underlayer wherein the first soft underlayer is thicker than the second soft underlayer (Fig. 2) is about 90 Oe.

According to the present invention, the exchange field increases with decreasing thickness of the second soft underlayer. This is illustrated by Fig. 5 for an underlayer 30 structure according to the present invention where the thickness of the second soft

underlayer is varied. The increase in exchange field further increases the anisotropy field of the soft underlayer. Therefore, the present invention provides a method to increase the anisotropy of the soft underlayer without adversely affecting the coercivity, magnetization or other properties.

5 A magnetic permeability of greater than about 100 in the soft underlayer is essential for good writability, whereas an even higher permeability value can lead to increased sensitivity to stray fields and also lead to adjacent track erasure of the media. The permeability of the soft underlayer is defined as:

$$4\pi M_S/H_k$$

10 where M_S is the saturation magnetization and H_k is the anisotropy field. The present invention advantageously provides an independent method to change the permeability of the soft underlayer by changing the anisotropy field.

15 Another embodiment of the present invention is illustrated in Fig. 6. In a manner similar to the embodiment illustrated in Fig. 2, the magnetic recording medium 600 illustrated in Fig. 6 includes a substrate 602, a soft underlayer structure 616, an intermediate layer 612 and a perpendicular magnetic recording layer 614. The soft underlayer structure 616 includes a first soft underlayer 606 and a second soft underlayer 610 that are separated by a non-magnetic spacer layer 608.

20 According to this embodiment, the underlayer structure 616 also includes an exchange enhancement layer 618 disposed between the non-magnetic spacer layer 608 and the second soft underlayer 610. This exchange enhancement layer 618 can be fabricated from Co or a Co-alloy such as CoCr or CoFe, for example, and has a preferred thickness of from about 1 to about 10 nanometers. The exchange enhancement layer 618 advantageously increases the exchange field, which in turn 25 increases the anisotropy field of the soft underlayer structure.

As is illustrated in Fig. 7, the adjacent track erasure for a conventional soft underlayer (Fig. 7a) and a soft underlayer according to the present invention (Fig. 7b) are illustrated. Adjacent track erasure is determined by writing 70 kfci tracks over a wide area. At the middle track position, a 425 kfci pattern is written 10,000 times. The

70 kfci signal is measured at each track and normalized to the original amplitude. The normalized amplitude for 100 tracks for media is illustrated in Fig. 7. The media with a conventional soft underlayer shows severe erasure that extends up to ± 25 mm on each side (the dip at zero cross-track position corresponds to the "stressing" track), which 5 corresponds to about 200 tracks near where the writing is occurring. On the other hand, the medium with a soft underlayer according to the present invention does not exhibit any adjacent track erasure.

Fig. 8 illustrates the signal to noise ratio (SNR) for a recording media fabricated using a conventional soft underlayer and a soft underlayer according to the present 10 invention, such as the embodiment illustrated in Fig. 2. The present invention allows the use of a thinner soft underlayer, such as down to about 100 nanometers, where a maximum SNR can be obtained. Higher SNR is very important for achieving higher areal density, whereas a thinner soft underlayer is essential for manufacturability and cost effectiveness of the perpendicular recording media.

15 According to another embodiment of the present invention, the saturation magnetization (M_s) of second soft underlayer is higher than the M_s of the first soft underlayer. According to this embodiment, the magnetic recording medium can have an overall structure similar to that illustrated in Fig. 2, however it is not necessary that 20 the first and second soft magnetic layers have a different thickness and according to this embodiment the layers can have substantially the same thickness. The first soft underlayer can be fabricated from materials such as CoZrTa, CoZrNb or the like whereas the second soft underlayer can be fabricated from materials such as FeCoB, CoFe and the like. For example, the M_s for CoZrTa is about 900 emu/cm², whereas 25 FeCoB is about 1500 emu/cm². Preferably, the saturation magnetization of the second soft underlayer is at least about 100 emu/cm² higher than the first soft underlayer, and more preferably is at least about 400 emu/cm² higher than the first soft underlayer.

30 The advantage of the foregoing embodiment in soft underlayer (SUL) noise reduction can be explained as follows. The magnetization patterns in the SUL follow the magnetic fringing fields from the written bits to form a flux closure pattern. A perfectly closed pattern with a small rotation angle is essential. Any uncompensated

magnetizations in the SUL could be a noise source for the reader. The anti-parallel exchange-coupling field increases with the decreased thickness of the layer. Therefore, a thinner second soft underlayer experiences a higher anti-parallel exchange field and the exchange field helps to create a small rotation angle for the SUL magnetization and

5 in turn reduces the noise. Higher M_s and a higher exchange field of the thinner second soft underlayer creates a sharp return path for the fringing field from the written bits and improves the SNR substantially.

Yet another embodiment of the present invention is illustrated in Fig. 9. The perpendicular recording medium 900 includes a soft underlayer structure 916 that

10 includes a thick first soft underlayer 906 and a thinner second soft underlayer 908 and third soft underlayer 910, separated by a first non-magnetic spacer layer 907, such as a carbon, Ta or Ta-oxide. The second soft underlayer 908 and third soft underlayer 910 are soft underlayers of approximately the same magnetization thickness product and are anti-parallel coupled through a second non-magnetic spacer layer 909, such as Ru.

15 The total thickness of layers 908, 909 and 910 can preferably be from about 20 to 80 nanometers and the thickness of the first soft underlayer 906 can preferably be from about 50 to 150 nanometers. In one example, the thickness of the first, second and third underlayers can be about 120 nanometers, 20 nanometers and 20 nanometers, respectively. According to this embodiment, while the total thickness of the three soft

20 underlayers serves as the flux return path during writing operations, the anti-parallel coupled SUL2/Ru/SUL3 structure decreases the noise from the SUL and also decreases the PW₅₀, particularly for thin intermediate layers.

While various embodiments of the present invention have been described in detail, it is apparent that modifications and adaptations of those embodiments will occur

25 to those skilled in the art. However, it is to be expressly understood that such modifications and adaptations are within the spirit and scope of the present invention.